

# HOUSTON COMMUNITY COLLEGE COURSE OUTLINE FOR

**Engineering Statics (ENGR 2301)** 

**Summer 2013** 

Class Number: 47868

## **Time and Location**

5:30 PM – 08:40 PM, Mon-Tue-Wed-Thurs, HCC Northwest College, Alief-Hayes Campus, Room Number B123

## **Instructor**

Bharat J. Sutaria

E-mail: bharat.sutaria@hccs.edu

Web address: <a href="http://learning.hccs.edu/faculty/bharat.sutaria">http://learning.hccs.edu/faculty/bharat.sutaria</a>

# **Course Intent and Description:**

Prerequisites: PHYS 2425 and MATH 2414

MATH 2414 (or higher).

Credit: 3 (3 lecture)(1 Problem Solving)

Composition and resolution of forces, free body diagrams, analysis of forces acting on structures and machines, friction, centroids, and moments of inertia

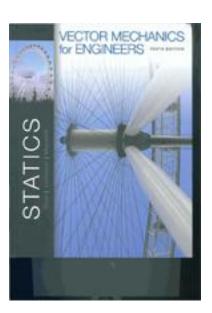
#### **Textbook**

# **Vector Mechanics for Engineers – Statics, 10<sup>th</sup> Edition**

Beer, Johnston, Mazurek, McGraw-Hill Publishers (2013)

ISBN-13 9780077889708, MHID 0077889703 (Statics only),

ISBN-13 9780073398136, MHID 0073398136 (Statics + Dynamics)



# **Additional Resources (Optional)**

# **Engineering Mechanics – Statics, 2<sup>nd</sup> Edition**

Plesha, Gray, Costanzo

McGraw-Hill Publishers (2013)

ISBN-13 9780077891138, MHID 0077891139 (Statics only),

ISBN-13 9780077891114, MHID 0077891112 (Statics + Dynamics)

# **Objectives**

Upon completion of this course students should be able to

- 1. Demonstrate qualitative and quantitative understanding of equilibrium of a particle and rigid bodies.
- 2. Develop the skill to isolate rigid bodies and draw clear and appropriate free-body diagrams and thereby apply this skill to solution of statics problems in 2-D and 3-D.
- 3. Determine centroids and center of gravity of 2-D and 3-D objects
- 4. Give analysis of structures, friction, and calculation of moment of inertia in two and three Dimensional objects.

## **Text book chapters:**

Depending on the progress of the class, following chapters will be covered in the order presented. This is subject to change as deemed necessary by the professor.

	1.1 What is Mechanics?						
	1.2 Fundamental Concepts and Principles						
1. NTRODUCTION	1.3 System of Units						
	1.4 Conversion from One System of Units to Anoth						
	1.5 Methods of Problem Solutions						
2. STATICS OF	2.1 Introduction						
PARTICLES	Forces in a Plane						
	2.2 Forces on a Particle: Resolution of Forces						
	2.3 Vectors						
	2.4 Addition of Vectors						
	2.5 Resultant of Several Concurrent Forces						
	2.6 Resolution of Forces into Components						
	2.7 Rectangular Components of a Force. Unit Vectors						
	2.8 Addition of Forces by Summing <i>x</i> and <i>y</i>						
	Components						
	2.9 Equilibrium of a Particle						
	2.10 Newton's First Law of Motion						
	2.11 Problems involving Equilibrium of a						
	Particle. Free-Body Diagrams						
	Tartiere. Tree Body Biagrams						
	Forces in Space						
	2.12 Rectangular Components of Forces in Space						
	2.13 Force Defined by its Magnitude and Two Points						
	on its Line of Action						
	2.14 Addition of Concurrent Forces in Space						
	3.1 Introduction						
3. RIGID BODIES:	3.2 External and Internal Forces						
<b>EQUIVALENT</b>	3.3 Principle of Transmissibility. Equivalent Forces						
SYSTEMS OF	3.4 Vector Product of Two Forces						
FORCES	3.5 Vector Products Expressed in Terms of						
	Rectangular Components						

	3.6 Moment of Force about a point			
	3.7 Varignon's Theorem			
	3.8 Rectangular Components of the Moment of			
	Forces			
	3.9 Scalar Product of Vectors			
	3.10 Mixed Triple Product of Three Vectors			
	3.11 Moment of a Force about a Given Axis			
	3.12 Moment of Couple			
	3.13 Equivalent Couples			
	3.14 Addition of Couples			
	3.15 Couples Can Be Represented by Vectors			
	3.16 Resolution of a Given Force Into a Force at <i>O</i>			
	and a Couple			
	3.17 Reduction of System of Forces to One Force and			
	One Couple			
	3.18 Equivalent System of Forces			
	3.19 Equipollent System of Forces			
	3.20 Further Reduction of System of Forces			
	<sup>1</sup> 3.21 Reduction of System of Forces to a Wrench			
	5.21 Reduction of System of Forces to a Wienen			
4. EQUILIBRIUM	4.1 Introduction			
OF RIGID BODIES	4.2 Free-Body Diagram			
	, ,			
	Equilibrium in Two Dimensions			
	4.3 Reactions at Supports and Connections for a			
	Two-Dimensional Structure			
	4.4 Equilibrium of Two Bodies in Two Dimensions			
	4.5 Statically Indeterminate Reactions, Partial			
	Constraints			
	4.6 Equilibrium of Two-Force Body			
	4.7 Equilibrium of Three-Force Body			
	1			
	Equilibrium In Three Dimensions			
	4.8 Equilibrium of a Rigid Body in Three Dimensions			
	4.9 Reactions at Supports and Connections for a			
	Three-Dimensional Structures			
	5.1 Introduction			
5. DISTRBUTED				
FORCES:	Areas and Lines			
CENTROIDS AND	5.2 Center of Gravity of a Two-Dimensional Body			
CENTERS	5.3 Centroids of Areas and Lines			
OFGRAVITY	5.4 First Moments of Areas and Lines			
OI GIMITIII	5.5 Composite Plates and Wires			
	5.6 Determination of Center of Gravity by Integration			
	5.7 Theorems of Pappus-Guldinus			
	*5.8 Distributed Loads on Beams			
	*5.9 Forces on submerged Surfaces			
i	5.7 Porces on submerged burraces			

	Volumes 5.10 Center of Gravity of a Three-dimensional Body:				
	Centroid of a Volume				
	5.11 Composite Bodies				
	5.12 Determination of Centeroids of Volumes by Integration				
	6.1 Introduction				
	Trusses				
	<ul><li>6.2 Definition of a Truss</li><li>6.3 Simple Trusses</li></ul>				
	6.4 Analysis of Trusses by the Method of Joints				
	*6.5 Joints under Special Loading Conditions				
6. ANALYSIS OF	*6.6 Space Trusses				
STRUCTURES	6.7 Analysis of Trusses by the Method of Sections				
	*6.8 Trusses Made up of Several Simple Trusses				
	Frames and Machines				
	6.9 Structures Containing Multiforce Members				
	6.10 Analysis of Frames				
	6.11 Frames which cease to Be Rigid When Detached				
	from their Supports 6.12 Machines				
	0.12 Machines				
*7. FORCES IN	7.1 Introduction				
BEAMS AND	7.2 Internal Forces in Members				
CABLES	Beams 7.2 Verious types of Loading and Supports				
	<ul><li>7.3 Various types of Loading and Supports</li><li>7.4 Shear and bending Moment in a Beam</li></ul>				
	7.5 Shear and Bending-Moment Diagrams				
	7.6 Relations among Load, Shear, and Bending				
	Moment				
	Cables				
	7.7 Cables with Concentrated Loads				
	7.8 Cables with Distributed loads				
	7.9 Parabolic Cable				
	7.10 Catenary				
8. FRICTION	8.1 Introduction				
	8.2 The Laws of Dry Friction, Coefficient of Friction				
	8.3 Angles of Friction				
	8.4 Problems Involving Dry Friction				
	8.5 Wedges 8.6 Square-Threaded Screws				
	*8.7 Journal Bearings, Axle Friction				
	*8.8 Thrust Bearings, Disk Friction				
	*8.9 Wheel Friction, Rolling Resistance				
	*8.10 Belt Friction				

9. DISTRIBUTED						
<b>FORCES:</b>						
MOMENTS OF	9.1 Introduction					
INERTIA	> 2 OGG (10)					
	Moments of Inertia of Areas					
	9.2 Second Moment, or Moment of Inertia of an Area					
	9.2 Second Moment, or Moment of Inertia of an Area 9.3 Determination of the Moment of Inertia of an					
	Area by integration					
	9.4 Polar Moment of Inertia					
	9.5 Radius of Gyration of an Area					
	9.6 Parallel Axis Theorem					
	9.7 Moment of Inertia of Composite Areas					
	*9.8 Product of Inertia					
	*9.9 Principal Axis and Principal Moments of Inertia					
	*9.10 Mohr's Circle for Moments and Products of					
	Inertia					
	11.01.01					
	Moments of Inartia of Massas					
	Moments of Inertia of Masses					
	9.11 Moments Of Inertia of a Mass					
	9.12 Parallel Axis Theorem					
	9.13 Moments of Inertia of a Thin Plate					
	9.14 Determination of the Moments of Inertia of a					
	Three Dimensional Body by Integration					
	9.15 Moments of Inertia of Composite Bodies					
	*9.16 Moment of Inertia of a Body with respect to an					
	Arbitrary Axis through O, Mass products of					
	Inertia					
	*9.17 Ellipsoid of Inertia, Principal Axis of Inertia					
	*0 12 Determination of the Principal Axis and					
	*9.18 Determination of the Principal Axis and					
	Principal Moments of Inertia of a Body of					
	Arbitrary Shape					
*10 METHOD OF	10.1 Letro dustion					
*10. METHOD OF	10.1 Introduction					
VIRTUAL WORK	10.2 Work of a Force					
	10.3 Principle of Virtual Work					
	10.4 Applications of the principle of Virtual Work					
	10.5 Real Machines, Mechanical Efficiency					
	10.6 Work of a Force during a Finite Displacement					
	10.7 Potential Energy					
	10.8 Potential Energy and Equilibrium					
	10.9 Stability of Equilibrium					
	10.2 Smothly of Equitoriality					

## **Attendance Policy**

The HCCS attendance policy is stated in the *Schedule of Classes*:

"Students are expected to attend classes regularly. Students are responsible for materials covered during their absences, and it is the student's responsibility to consult with instructors for make-up assignments. Class attendance is checked daily by instructors. Although it is the responsibility of the student to drop a course for non-attendance, the instructor has full authority to drop a student for excessive absences. A student may be dropped from a course for excessive absences after the student has accumulated absences in excess of 12.5% of the hours of instruction (including lecture and laboratory time)."

If circumstances significantly prevent you from attending classes, please inform me. I realize that sometimes outside circumstances can interfere with school, and I will try to be as accommodating as possible, but please be aware of the attendance policy.

### **Last Day for Administrative and Student Withdrawals**

This date is stated in the *Schedule of Classes*. After the withdrawal date, no "W" can be given, and you must receive a regular grade (A-F) in the course. I urge any student who is contemplating withdrawing from the class to see me first. You may be doing better than you think. Either way, I want to be accessible and supportive. I do not believe in "weed out" classes, and I consider you to be much more than just a name or number. If you need assistance, do not hesitate to contact me (my e-mail address is listed above). I am here to help.

#### **IMPORTANT NOTICE**

Students who repeat a course three or more times may soon face significant tuition/fee increases at HCC and other Texas public colleges and universities. If you are considering course withdrawal because you are not earning passing grades, confer with your instructor/counselor as early as possible about your study habits, reading and writing homework, test-taking skills, attendance, course participation, and opportunities for tutoring or other assistance that might be available.

#### **Disability Support Services (DSS)**

HCCS is committed to compliance with the Americans with Disabilities Act and the Rehabilitation Act of 1973 (section 504).

"Any student with a documented disability (e.g. physical, learning, psychiatric, vision, hearing, etc.) who needs to arrange reasonable accommodations must contact the Disability Services Office at the respective college at the beginning of each semester. Faculty is authorized to provide only the accommodations requested by the Disability Support Services Office."

If you have any special needs or disabilities which may affect your ability to succeed in college classes or participate in college programs/activities, please contact the office of disability support services at the college. Upon consultation and documentation, you will be provided with reasonable accommodations and/or modifications. Please contact the DSS office as soon as you begin the term.

# **Academic Honesty**

Students are responsible for conducting themselves with honor and integrity in fulfilling course requirements. Disciplinary proceedings may be initiated by the college system against a student accused of scholastic dishonesty. Penalties can include a grade of "0" or "F" on the particular assignment, failure in the course, academic probation, or even dismissal from the college. Scholastic dishonesty includes, but is not limited to, cheating on a test, plagiarism, and collusion.

## **Email/Telephone Communication:**

Professor will communicate using your Email address and/or dialing your phone number as needed. It is student's responsibility to verify and update their Email address and their phone number on HCC database. The professor will not use any other email address and phone number except the one listed on HCC database for students. Read your Email regularly. "I did not read my Email" and/or "That is not my phone number" will not be an accepted excuse to settle any issues.

## **Grading**

The *overall score* is comprised of the following:

Attendance: 20% Exam I: 20% Exam II: 20%

Exam III: 20% Exam IV: 20%

- Note: Attendance is 20% of your final grade. If you are tardy or leave early, it will be counted as half absence.
- Generally, there is no makeup if you missed a test. I may try (No guarantees) to let you make up test if you have a valid and verifiable excuse. However, regardless of the reason, there will be a twenty point penalty.

The *course grade* is then obtained from the overall score:

Final Score	90 - 100	80 – 89	70 – 79	60 – 69	< 60
Letter Grade	A	В	С	D	F

Please note: After the withdrawal date, no "W" can be given, and you <u>must</u> receive a regular grade, (A-F) in the course.

## **Exam Schedule and other course related dates dates**

In general, the schedule below will be followed. Deviation from this schedule may be necessary from time to time and will be conveyed to the class. Students are expected to bring up to professor's attention any confusion or contradiction to this schedule, class room announcements and HCC web site.

Monday, June 3, 2013: Orientation, Introduction, Syllabus, Instruction starts

Tuesday, June 11, 2013: Exam I
Wednesday, June 19, 2013: Exam II
Wednesday, June 26, 2013: Exam III
Wednesday, July 3, 2013: Exam IV

#### **Other Important Dates**

It is students' responsibility to visit HCC web site for all important dates, deadlines, holidays, etc. Students are expected to bring any discrepancies/issues regarding these dates to professor's attention in timely manner.

#### **Other Information**

- Free tutoring may be available. Verify availability with the Professor or Department Chair.
- There are many interesting resources on the Internet. These are interesting and informative, but your best immediate source of information is your textbook make thorough use of it.

# **Suggestions**



Attend class regularly and take generous notes during class. Ask questions.



Read the chapter before it is scheduled to be taught in class. You will understand what is going on in class much better if you do.



Start tackling the end-of-chapter problems. Working through the problems facilitates understanding much better than just reading and re-reading the chapter itself.



Get a good, <u>scientific</u> calculator that has scientific notation ("EE" or "EXP" key, log, ln,  $x^2$ ,  $\sqrt{}$ , etc.). Business calculators usually do not have all of these features.



Review basic math operations, if needed.



Study groups can be very helpful. Keep groups small (no more than three or four people).



Maintain a positive attitude. Class can be difficult, but with the right attitude and approach, you will succeed!

#### **Final Remarks**

I hope you find Engineering Statics to be an interesting and rewarding subject, which will not only be useful in your academic major, but will give you better insight into the many scientific challenges we are facing today. I look forward to working with you this semester.